

Case (iii) Repeated eigenvectors (2x2 case)

If λ is an eigenvalue with eigenvector $\vec{v}_1$, then

$$\vec{X} = c_1 e^{\lambda t} \vec{v}_1 + c_2 e^{\lambda t} (\vec{v}_1 t + \vec{v}_2)$$

where $(A - \lambda I)\vec{v}_2 = \vec{v}_1$ ($\vec{v}_2$ is called the generalized eigenvector)

Ex Solve the system $\vec{X}' = \begin{pmatrix} 3 & -18 \\ 2 & -9 \end{pmatrix} \vec{X}$

① eigenvalues $\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & -18 \\ 2 & -9-\lambda \end{vmatrix} = (3-\lambda)(-9-\lambda) + 36$

$$-27 - 3\lambda + 9\lambda + \lambda^2 + 36 = 0 \Rightarrow \lambda^2 + 6\lambda + 9 = 0 \Rightarrow (\lambda + 3)^2 = 0$$

$\lambda = -3$ mult 2

② eigenvectors

$$(A - \lambda I)\vec{v}_1 = 0: \begin{pmatrix} 3-(-3) & -18 \\ 2 & -9-(-3) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \sim \begin{pmatrix} 6 & -18 \\ 2 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$2x_1 = 6x_2$
 $x_1 = 3x_2$ $\vec{v}_1 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

$$(A - \lambda I)\vec{v}_2 = \vec{v}_1: \begin{pmatrix} 3-(-3) & -18 \\ 2 & -9+3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \sim \begin{pmatrix} 6 & -18 \\ 2 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

$2x_1 = 6x_2 + 1$
 $x_1 = 3x_2 + \frac{1}{2}$
 $x_2 = 0$ $\vec{v}_2 = \begin{pmatrix} 1/2 \\ 0 \end{pmatrix}$

$$\vec{X} = c_1 e^{-3t} \begin{pmatrix} 3 \\ 1 \end{pmatrix} + c_2 e^{-3t} \left[\begin{pmatrix} 3 \\ 1 \end{pmatrix} t + \begin{pmatrix} 1/2 \\ 0 \end{pmatrix} \right]$$

Nonhomogeneous Linear Systems - Undetermined Coefficients

Want to solve equations of the form $\vec{X}' = A\vec{X} + \vec{g}(t)$.

where $\vec{g}(t)$ is a vector ^(or vector) of exponential functions, polynomials, sine/cosine functions or any sum or product of these functions.

- Steps to Solve
- (1) Write in standard form: $\vec{x}' = A\vec{x} + \vec{g}(t)$
 - (2) Solve for homogeneous solution $\vec{x}_h$ ($\vec{x}' = A\vec{x}$)
 - (3) Guess $\vec{x}_p$
 - (4) Plug $\vec{x}_p$ in and solve for coefficients
 - (5) $\vec{x} = \vec{x}_p + \vec{x}_h$

How to guess? Similar to before...

$\vec{g}(t)$	$\vec{x}_p$
$\begin{pmatrix} 100 \\ 0 \end{pmatrix} e^t$	$\vec{a} e^t = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^t$
$\begin{pmatrix} 18 \\ -2 \end{pmatrix} t^2 - \begin{pmatrix} 4 \\ 3 \end{pmatrix} t$	$\vec{a} t^2 + \vec{b} t + \vec{c} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} t^2 + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} t + \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$
$\begin{pmatrix} 10 \\ 10 \end{pmatrix} \cos 2t$ $\begin{pmatrix} 3 \\ 1 \end{pmatrix} \cos 2t$	$\vec{a} \sin 2t + \vec{b} \cos 2t = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin 2t + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos 2t$

What happens if $\vec{g}(t)$ has functions in common with $\vec{x}_h$?
a little different than before

Ex Suppose $\vec{x}_h = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^t + c_2 \begin{pmatrix} 3 \\ 4 \end{pmatrix}$, $\vec{g}(t) = \begin{pmatrix} 9 \\ 4 \end{pmatrix}$. Find form of $\vec{x}_p$.

Guess: $\vec{x}_p = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$ but already shows up in $\vec{x}_h$. ($c_2 \begin{pmatrix} 3 \\ 4 \end{pmatrix}$)

$$\vec{x}_p = \vec{a}t + \vec{b} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} t + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

Ex Suppose $\vec{x}_h = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} e^t + c_2 \begin{pmatrix} 3 \\ 4 \end{pmatrix}$, $\vec{g}(t) = \begin{pmatrix} -3 \\ 1 \end{pmatrix} e^t + \begin{pmatrix} 9 \\ 4 \end{pmatrix}$. Find form of $\vec{x}_p$.

Guess: $\vec{x} = \cancel{\vec{a}t + \vec{b}} = \underline{\underline{\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} e^t}} + \underline{\underline{\begin{pmatrix} b_1 \\ b_2 \end{pmatrix}}}$ already part of $\vec{x}_h$

$$\vec{x} = \vec{a}t e^t + \vec{b} e^t + \vec{c}t + \vec{d} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} t e^t + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} e^t + \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} t + \begin{pmatrix} d_1 \\ d_2 \end{pmatrix}$$

Ex Solve $\begin{cases} \frac{dx}{dt} = 5x + 9y + 2 \\ \frac{dy}{dt} = -x + 11y + 6 \end{cases}$

① standard form $\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 5 & 9 \\ -1 & 11 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \end{pmatrix}$
 $\vec{x}' = \begin{pmatrix} 5 & 9 \\ -1 & 11 \end{pmatrix} \vec{x} + \begin{pmatrix} 2 \\ 6 \end{pmatrix}$

② Solve $\vec{x}' = \begin{pmatrix} 5 & 9 \\ -1 & 11 \end{pmatrix} \vec{x}$.

$\begin{vmatrix} 5-\lambda & 9 \\ -1 & 11-\lambda \end{vmatrix} = 0 \Rightarrow (5-\lambda)(11-\lambda) + 9 = 55 - 16\lambda + \lambda^2 + 9 = \lambda^2 - 16\lambda + 64$
 $= (\lambda - 8)^2 = 0 \Rightarrow \lambda = 8 \text{ mult } 2$

$\left(\begin{array}{cc|c} 5-8 & 9 & 0 \\ -1 & 11-8 & 0 \end{array} \right) \sim \left(\begin{array}{cc|c} -3 & 9 & 0 \\ -1 & 3 & 0 \end{array} \right)$ $\begin{matrix} -x_1 + 3x_2 = 0 \\ x_1 = 3x_2 \end{matrix}$ $x_1=0 \Rightarrow \vec{v}_1 = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$

$\left(\begin{array}{cc|c} -3 & 9 & 3 \\ -1 & 3 & 1 \end{array} \right)$ $\begin{matrix} -x_1 + 3x_2 = 1 \\ x_1 = 3x_2 - 1 \end{matrix}$ $x_2=0 \Rightarrow \vec{v}_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$

$\vec{x}_h = c_1 \begin{pmatrix} 3 \\ 1 \end{pmatrix} e^{8t} + c_2 e^{8t} \left[\begin{pmatrix} 3 \\ 1 \end{pmatrix} t + \begin{pmatrix} -1 \\ 0 \end{pmatrix} \right]$

③ $\vec{g}(t) = \begin{pmatrix} 2 \\ 6 \end{pmatrix}$ $\vec{x}_p = \vec{a} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$

④ $\vec{x}_p' = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 5 & 9 \\ -1 & 11 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \end{pmatrix}$

$\begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 5a_1 + 9a_2 + 2 \\ -a_1 + 11a_2 + 6 \end{pmatrix}$

$\begin{cases} 5a_1 + 9a_2 = -2 \\ -a_1 + 11a_2 = -6 \end{cases} \Rightarrow \begin{matrix} 5a_1 + 9a_2 = -2 \\ -5a_1 + 55a_2 = -30 \\ \hline 64a_2 = -32 \end{matrix} \Rightarrow a_2 = -1/2$

$a_1 = 11a_2 + 6$
 $a_1 = -11/2 + 6 = 1/2 \Rightarrow \vec{x}_p = \begin{pmatrix} 1/2 \\ -1/2 \end{pmatrix}$

⑤ $\vec{x} = \vec{x}_h + \vec{x}_p \Rightarrow \boxed{\vec{x} = c_1 \begin{pmatrix} 3 \\ 1 \end{pmatrix} e^{8t} + c_2 e^{8t} \left[\begin{pmatrix} 3 \\ 1 \end{pmatrix} t + \begin{pmatrix} -1 \\ 0 \end{pmatrix} \right] + \begin{pmatrix} 1/2 \\ -1/2 \end{pmatrix}}$

Stability and Classification

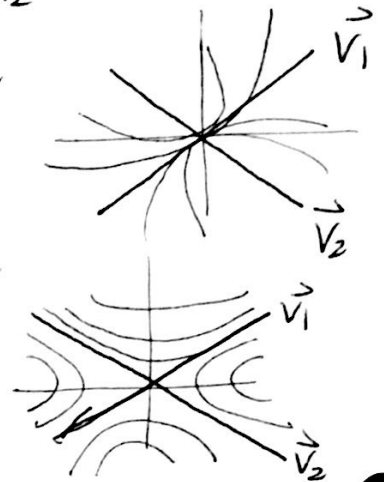
$$\vec{x}' = A\vec{x} \quad A \text{ } 2 \times 2$$

If $\lim_{t \rightarrow \infty} \vec{x} \xrightarrow{\text{converges}}$, we say that the solution is stable.

Otherwise it is unstable.

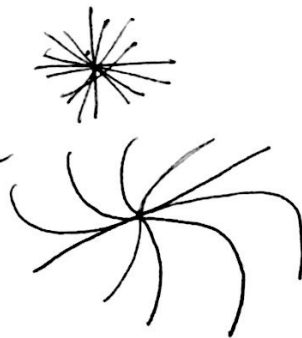
Classification: (i) Real, distinct eigenvalues λ_1, λ_2

- λ_1, λ_2 same sign: node
+ unstable
- stable
- λ_1, λ_2 opposite sign: saddle
always unstable



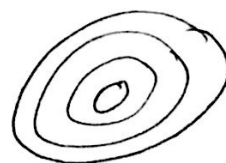
(ii) Real, repeated eigenvalue λ + unstable, - stable

- two L.T eigenvectors: star
- one eigenvector: degenerate node



(iii) complex eigenvalues

- real part = 0 center (stable)



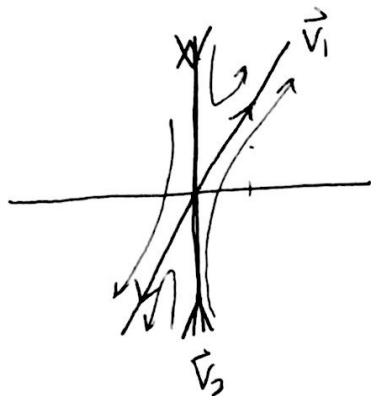
- real part $\neq 0$ spiral
real part + unstable
real part - stable



Previous examples...

Ex (a) $\vec{x}' = \begin{pmatrix} 3 & 0 \\ 8 & -1 \end{pmatrix} \vec{x}$ has solution $\vec{x} = c_1 e^{3t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$\lambda_1 = 3, \lambda_2 = -1$ opposite signs $\Rightarrow$ saddle, unstable



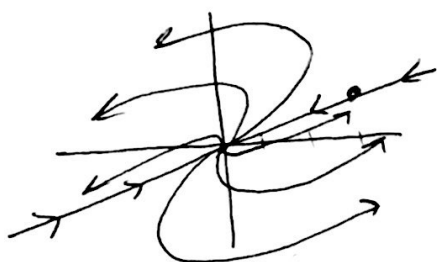
plot $\vec{v}_1, \vec{v}_2$

$\vec{v}_1$ outward arrow (diverges)

$\vec{v}_2$ inward arrow (converges)

(b) $\vec{x}' = \begin{pmatrix} 3 & -18 \\ 2 & -9 \end{pmatrix} \vec{x}$ has solution $\vec{x} = c_1 e^{-3t} \begin{pmatrix} 3 \\ 1 \end{pmatrix} + c_2 e^{-3t} \left[\begin{pmatrix} 3 \\ 1 \end{pmatrix} t + \begin{pmatrix} 1/2 \\ 0 \end{pmatrix} \right]$

$\lambda_1 = -3$ stable, degenerate node



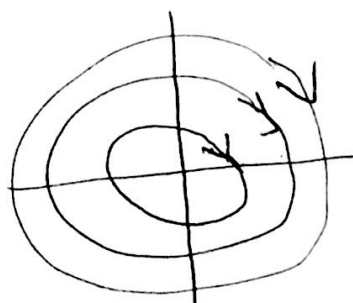
plot $\vec{v}_1$ (inward arrow)

direction: look at tangent to a point

at $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$: $\vec{x}' = \begin{pmatrix} 3 & -18 \\ 2 & -9 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$
upward

(c) $\vec{x}' = \begin{pmatrix} 2 & 8 \\ -1 & -2 \end{pmatrix} \vec{x}$ has solution $\vec{x} = c_1 \begin{pmatrix} -2 \cos 2t + 2 \sin 2t \\ \cos 2t \end{pmatrix} + c_2 \begin{pmatrix} -2 \sin 2t - 2 \cos 2t \\ \sin 2t \end{pmatrix}$

$\lambda = \pm 2i$ real part 0 $\Rightarrow$ center, stable



find tangent at point for direction:

$\vec{x}' = \begin{pmatrix} 2 & 8 \\ -1 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$ downward clockwise