

# Math 33A – Week 5

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Name: KEY

1. Let  $T(\mathbf{x}) = \begin{pmatrix} 1 & -3 & 0 & -5 \\ 0 & 0 & 1 & 2 \end{pmatrix} \mathbf{x}$ .

(a) Find  $\text{im}(T)$  and  $\ker(T)$ .

$$\left( \begin{array}{cccc|c} 1 & -3 & 0 & -5 & 0 \\ 0 & 0 & 1 & 2 & 0 \end{array} \right) \text{ already in rref.}$$

↑  
↑  
↑  
↑  
free free free  
1st and 3rd columns  
span  $\text{im } T$

$$\text{im } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

$x_2$  free,  $x_2 = t$   
 $x_4$  free,  $x_4 = s$

$$x_1 - 3x_2 - 5x_4 = 0 \rightarrow x_1 = 3x_2 + 5x_4$$

$$x_3 + 2x_4 = 0 \rightarrow x_3 = -2x_4$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 3t + 5s \\ t \\ -2s \\ s \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 0 \\ 0 \end{pmatrix} t + \begin{pmatrix} 5 \\ 0 \\ -2 \\ 1 \end{pmatrix} s$$

$$\ker T = \text{span} \left\{ \begin{pmatrix} 3 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 5 \\ 0 \\ -2 \\ 1 \end{pmatrix} \right\}$$

(b) Verify the rank-nullity theorem for this transformation.

$$\begin{array}{ll} \text{rank} = 2 & \text{rank} + \text{nullity} = 4 = \# \text{ of columns of } \begin{pmatrix} 1 & -3 & 0 & -5 \\ 0 & 0 & 1 & 2 \end{pmatrix} \checkmark \\ \text{nullity} = 2 & \end{array}$$

(c) Are there any vectors  $\mathbf{y} \in \mathbb{R}^2$  such that  $\mathbf{y} \notin \text{im}(T)$ ? \*Remark: This illustrates that  $\text{im } T = \mathbb{R}^2$

One way: for  $\vec{y} \in \text{im } T$  means  $T(\vec{x}) = \vec{y}$  for some  $\vec{x}$

$$\Rightarrow \left( \begin{array}{cccc|c} 1 & -3 & 0 & -5 & y_1 \\ 0 & 0 & 1 & 2 & y_2 \end{array} \right) \text{ Q: is it possible for this system to have no solution?}$$

A: No, this system always has a solution no matter the value of  $\vec{y}$

No, no  $\vec{y}$  such that  $\vec{y} \notin \text{im } T$

Another way: in (a) we find  $\text{im } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$

For  $\vec{y} \in \text{im } T$  means there are  $a, b$  s.t.  $a \begin{pmatrix} 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \vec{y}$

$$\Rightarrow \left( \begin{array}{c|c} 1 & y_1 \\ 0 & y_2 \end{array} \right) \text{ Q: is it possible for this system to have no solution?}$$

A: no, this system always has a solution no matter the value of  $\vec{y}$ .

No, no  $\vec{y}$  such that  $\vec{y} \notin \text{im } T$

2. Recall that  $T(\mathbf{x}) = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x}$  is the transformation that projects  $\mathbf{x} = (x, y)$  onto the  $y$ -axis.

(a) Without solving explicitly, what do you expect  $\text{im}(T)$  and  $\ker(T)$  to be? (You don't need to use set notation here, you can write a short description about what you think they will be.)

$\text{im } T = \text{all outputs of } T(\vec{x}) = y\text{-axis}$

$\ker T = \text{all inputs } \vec{x} \text{ s.t. } T(\vec{x}) = \vec{0} \Rightarrow \ker T = x\text{-axis}$

(b) Solve  $\text{im}(T)$  and  $\ker(T)$  explicitly. Do these match your intuition in (a)?

$$\left( \begin{array}{cc|c} 0 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cc|c} 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

free  
↑  
2nd column of  
original matrix  
span  $\text{im } T$

$$\text{im } T = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

↑  
this is the  $y$ -axis

$x_1$  free,  $x_1 = t$   
 $x_2 = 0$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} t \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} t$$

$$\ker T = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$

↑  
this is the  $x$ -axis!

(c) Verify the rank-nullity theorem for this transformation.

$$\begin{array}{ll} \text{rank} = 1 & \text{rank} + \text{nullity} = 2 = \# \text{ of columns of } \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \\ \text{nullity} = 1 & \end{array}$$

(d) Find a vector  $\mathbf{y}$  such that  $\mathbf{y} \notin \text{im}(T)$ . \* answers will vary

$\vec{y} \in \text{im } T$  means  $T(\vec{x}) = \vec{y}$  for some  $\vec{x}$

$$\left( \begin{array}{cc|c} 0 & 0 & y_1 \\ 0 & 1 & y_2 \end{array} \right) \quad \begin{array}{l} \text{If } y_1 \text{ is a nonzero } \# \text{ then} \\ \text{this system has no solution!} \end{array}$$

e.g.  $\vec{y} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  since the vector  $\vec{y} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin \text{im } T$  since  $\left( \begin{array}{cc|c} 0 & 0 & 1 \\ 0 & 1 & 1 \end{array} \right)$  has no solution

(e) Is  $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$  invertible? no,  $\det \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = 0 \cdot 1 - 0 \cdot 0 = 0$

3. Recall that  $T(\mathbf{x}) = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \vec{x}$  is the transformation that rotates  $\mathbf{x}$  by  $\frac{\pi}{4}$  radians and stretches the rotated vector by a factor of  $\sqrt{2}$ .

(a) Without solving explicitly, what do you expect  $\text{im}(T)$  and  $\text{ker}(T)$  to be? (You don't need to use set notation here, you can write a short description about what you think they will be.)

$\text{im } T = \text{all outputs} = \mathbb{R}^2$  since if we rotate  $\mathbb{R}^2$  by  $\frac{\pi}{4}$  and scale by  $\sqrt{2}$  we still get  $\mathbb{R}^2$

$$\text{ker } T = \text{all inputs } \vec{x} \text{ s.t. } T(\vec{x}) = \vec{0} \Rightarrow \text{ker } T = \{ \vec{0} \}$$

(b) Solve  $\text{im}(T)$  and  $\text{ker}(T)$  explicitly. Do these match your intuition in (a)?

$$\left( \begin{array}{cc|c} 1 & -1 & 0 \\ 1 & 1 & 0 \end{array} \right) \xrightarrow{R_1 + R_2 \rightarrow R_2} \left( \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 2 & 0 \end{array} \right) \xrightarrow{\frac{1}{2}R_2 \rightarrow R_2} \left( \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 1 & 0 \end{array} \right) \xrightarrow{R_1 + R_2 \rightarrow R_1} \left( \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \end{array} \right) \quad \begin{array}{l} \text{this system has the unique solution} \\ (\vec{x}_1, \vec{x}_2) = (0, 0) \end{array}$$

1st and 2nd columns of original matrix span  $\text{im } T$

$\text{im } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$

$\Rightarrow \boxed{\text{ker } T = \{ \vec{0} \}}$

(c) Verify the rank-nullity theorem for this transformation.

$$\begin{array}{ll} \text{rank} = 2 & \text{rank} + \text{nullity} = 2 = \# \text{ of columns of } \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \\ \text{nullity} = 0 & \end{array}$$

(d) Are there any vectors  $\mathbf{y} \in \mathbb{R}^2$  such that  $\mathbf{y} \notin \text{im}(T)$ ? \* Remark: This illustrates that  $\text{im } T = \mathbb{R}^2$

One way  $\vec{y} \in \text{im } T$  means  $T(\vec{x}) = \vec{y}$  for some  $\vec{x}$

$$\left( \begin{array}{cc|c} 1 & -1 & y_1 \\ 1 & 1 & y_2 \end{array} \right) \xrightarrow{\text{row operations}} \left( \begin{array}{cc|c} 1 & 0 & \text{shift} \\ 0 & 1 & \end{array} \right)$$

This system always has a solution  $\Rightarrow \boxed{\text{No } \vec{y} \text{ s.t. } \vec{y} \notin \text{im } T}$

Another way in (b),  $\text{im } T = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$

$$\vec{y} \in \text{im } T \text{ means there are } a, b \text{ s.t. } a \begin{pmatrix} 1 \\ 1 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \vec{y}$$

$$\left( \begin{array}{cc|c} 1 & -1 & y_1 \\ 1 & 1 & y_2 \end{array} \right) \leftarrow \text{this system always has a solution after doing row operations} \Rightarrow \boxed{\text{No } \vec{y} \text{ s.t. } \vec{y} \notin \text{im } T}$$

(e) Is  $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$  invertible? yes,  $\det \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = 1 \cdot 1 - (-1) \cdot 1 = 1 + 1 = 2 \neq 0$

4. The invertibility of a square matrix is related to its rank, nullity, kernel, and image. The matrix  $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$  in Exercise 2 is not invertible, but  $\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$  in Exercise 3 is invertible. Fill in the following statements below (you can use Exercises 2 and 3 for reference):

- (a) If  $A$  is an  $n \times n$  matrix and  $\text{rank}(A) = \underline{n}$ , then  $\text{im}(A) = \mathbb{R}^n$ .
- (b) If  $A$  is an  $n \times n$  matrix and  $\text{rank}(A) = n$ , then  $\text{nullity}(A) = \underline{0}$ .
- (c) If  $A$  is an  $n \times n$  matrix and  $\text{nullity}(A) = \underline{0}$ , then  $\text{ker}(A) = \{\mathbf{0}\}$ .
- (d) If  $A$  is an  $n \times n$  matrix and  $\text{ker}(A) = \underline{\{\mathbf{0}\}}$ , then  $A$  is invertible.
- (e) If  $A$  is an  $n \times n$  matrix and  $\text{rank}(A) \neq \underline{n}$ ,  $A$  is not invertible.
- (f) If  $A$  is an  $n \times n$  matrix and  $\text{nullity}(A) \neq \underline{0}$ ,  $A$  is not invertible.
- (g) If  $A$  is an  $n \times n$  matrix and  $\text{ker}(A) \neq \{\mathbf{0}\}$ ,  $A$  is not invertible.