

Math 33B Worksheet 7 (Phase Plane for Linear Systems)

Name: KEY Score: _____

Circle the name of your TA: Ziheng Nicholas Victoria

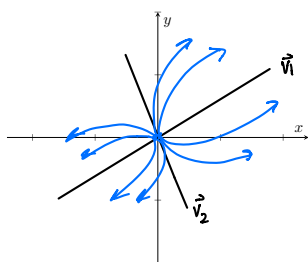
Circle the day of your discussion: Tuesday Thursday

1. The linear system

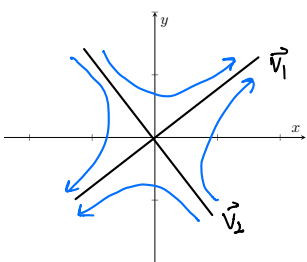
$$\begin{aligned}x' &= ax + by \\y' &= cx + dy\end{aligned}$$

can be written in matrix form $\mathbf{x}' = A\mathbf{x}$ where $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. We can use the eigenvalues and eigenvectors of A to sketch the phase plane/portrait for the system. Below are the possible behaviors for linear systems with nonzero eigenvalues, sketch a plausible phase portrait for each behavior.

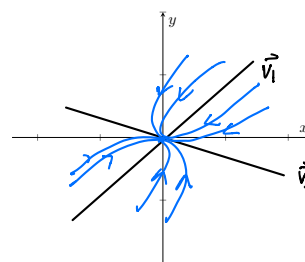
(i) Real, distinct eigenvalues ($\lambda_1 \neq \lambda_2$)



unstable node
($\lambda_1 > \lambda_2 > 0$)

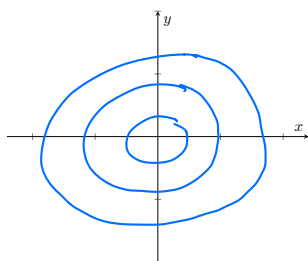


saddle
($\lambda_1 > 0 > \lambda_2$)

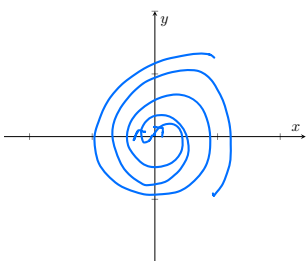


stable node
($\lambda_1 < \lambda_2 < 0$)

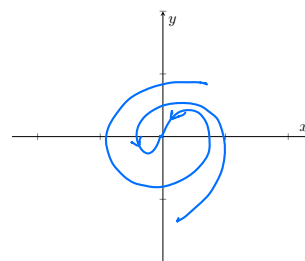
(ii) Complex eigenvalues ($\lambda = \alpha \pm \beta i$)



center
($\alpha = 0$)



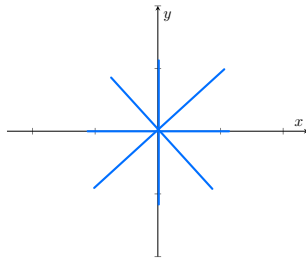
stable spiral
($\alpha < 0$)



unstable spiral
($\alpha > 0$)

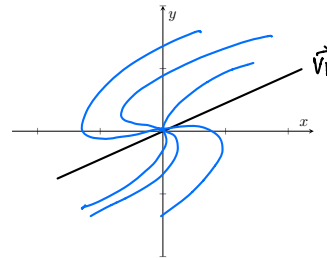
Question: How do we determine whether the center or spiral is clockwise or counter-clockwise?

(iii) Real repeated eigenvalues



star node

Occurs when $A = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$



degenerate node

Occurs when $A = \begin{pmatrix} \lambda & b \\ 0 & \lambda \end{pmatrix}$

Question: When are each of these nodes stable or unstable?

2. Consider the linear system

$$\begin{aligned} x' &= x + y \\ y' &= 4x - 2y. \end{aligned}$$

(a) Rewrite this system in matrix form $\mathbf{x}' = A\mathbf{x}$. Find the eigenvalues of A and use these to classify the behavior and stability of the system.

$$\dot{\vec{x}} = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \vec{x} \quad \left| \begin{array}{cc|c} 1-\lambda & 1 & 0 \\ 4 & -2-\lambda & 0 \end{array} \right| = (1-\lambda)(-2-\lambda) - 4 = -2 - \lambda + 2\lambda + \lambda^2 - 4 = \lambda^2 + \lambda - 6 = (\lambda+3)(\lambda-2)$$

$$\lambda_1 = -3 \quad \lambda_2 = 2$$

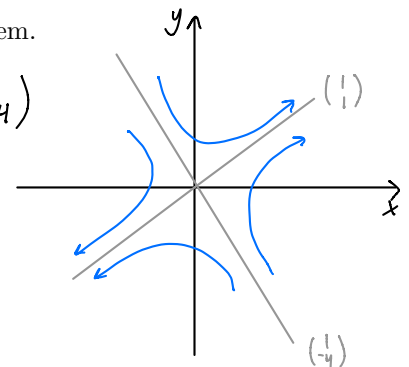
opposite signs \Rightarrow saddle
unstable

(b) Find the eigenvectors of A and sketch the phase portrait of the system.

$$\lambda_1 = -3: \left(\begin{array}{cc|c} 1-(-3) & 1 & 0 \\ 4 & -2-(-3) & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 4 & 1 & 0 \\ 4 & 1 & 0 \end{array} \right) \quad \begin{aligned} 4x_1 + x_2 &= 0 \\ x_2 &= -4x_1 \end{aligned} \quad \vec{v}_1 = \begin{pmatrix} 1 \\ -4 \end{pmatrix}$$

$$\lambda_2 = 2: \left(\begin{array}{cc|c} 1-2 & 1 & 0 \\ 4 & -2-2 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} -1 & 1 & 0 \\ 4 & -4 & 0 \end{array} \right) \quad \begin{aligned} -x_1 + x_2 &= 0 \\ x_1 &= x_2 \end{aligned} \quad \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

dominant
eigenvector



3. Consider the linear system

$$\begin{aligned}x' &= 4x - y \\y' &= 2x + y.\end{aligned}$$

- (a) Rewrite this system in matrix form $\mathbf{x}' = A\mathbf{x}$. Find the eigenvalues of A and use these to classify the behavior and stability of the system.

$$\vec{x}' = \begin{pmatrix} 4 & -1 \\ 2 & 1 \end{pmatrix} \vec{x} \quad \left| \begin{array}{cc|c} 4-\lambda & -1 & 0 \\ 2 & 1-\lambda & 0 \end{array} \right| = (4-\lambda)(1-\lambda) + 2 = 4 - 4\lambda - \lambda + \lambda^2 + 2 = \lambda^2 - 5\lambda + 6 = (\lambda-3)(\lambda-2)$$

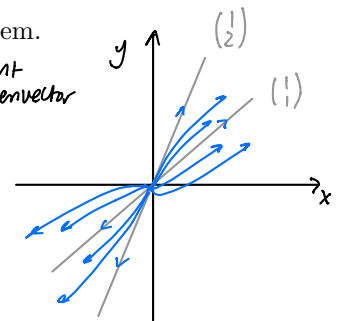
$$\lambda_1 = 3 \quad \lambda_2 = 2$$

same sign \rightarrow unstable node

- (b) Find the eigenvectors of A and sketch the phase portrait of the system.

$$\lambda_1 = 3: \left(\begin{array}{cc|c} 4-3 & -1 & 0 \\ 2 & 1-3 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 1 & -1 & 0 \\ 2 & -2 & 0 \end{array} \right) \quad x_1 = x_2 \quad \vec{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \text{ dominant eigenvector}$$

$$\lambda_2 = 2: \left(\begin{array}{cc|c} 4-2 & -1 & 0 \\ 2 & 1-2 & 0 \end{array} \right) \rightarrow \left(\begin{array}{cc|c} 2 & -1 & 0 \\ 2 & -1 & 0 \end{array} \right) \quad x_2 = 2x_1 \quad \vec{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$



4. Consider the linear system

$$\begin{aligned}x' &= x - y \\y' &= x + y.\end{aligned}$$

- (a) Rewrite this system in matrix form $\mathbf{x}' = A\mathbf{x}$. Find the eigenvalues of A and use these to classify the behavior and stability of the system.

$$\vec{x}' = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \vec{x} \quad \left| \begin{array}{cc|c} 1-\lambda & -1 & 0 \\ 1 & 1-\lambda & 0 \end{array} \right| = (1-\lambda)^2 + 1 = \lambda^2 - 2\lambda + 1 + 1 = \lambda^2 - 2\lambda + 2$$

$$\lambda = \frac{2 \pm \sqrt{4 - 4(1)(2)}}{2(1)} = \frac{2 \pm \sqrt{-4}}{2} = \frac{2 \pm 2i}{2}$$

$$\lambda = 1 \pm i$$

$\text{Re } \lambda = 1 > 0$ unstable spiral

- (b) The eigenvalues in (a) are complex with nonzero real part. Come up with a way to determine whether the spiral is clockwise or counterclockwise, then sketch the phase portrait of the system.

Plug in points to see what vector field is doing.

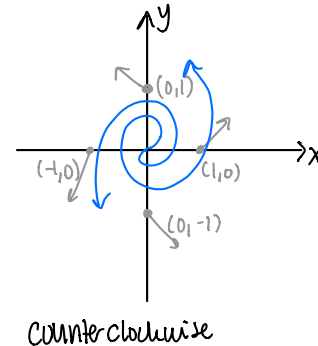
$$\begin{aligned}x' &= x - y \\y' &= x + y\end{aligned}$$

At $(1,0)$ $x' = 1$ i.e. right and up

At $(0,1)$ $x' = -1$ i.e. left and up

At $(-1,0)$ $x' = -1$ i.e. left and down

At $(0,-1)$ $x' = 1, y' = -1$ i.e. right and down



5. **Simple Harmonic Oscillator.** The vibrations of a mass hanging from a linear spring are governed by the linear differential equation

$$mx'' + kx = 0$$

where m is the mass, k is the spring constant, and x is the displacement of the mass from the equilibrium. We can rewrite this second order differential equation as the first order system

$$x' = v$$

$$v' = -\omega^2 x$$

where $\omega^2 = k/m$. Plot the phase portrait for this system. What do these closed orbits represent?

$$\begin{pmatrix} x \\ v \end{pmatrix}' = \begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix} \begin{pmatrix} x \\ v \end{pmatrix} \quad \text{eigenvalues: } \begin{vmatrix} -\lambda & 1 \\ -\omega^2 & -\lambda \end{vmatrix} = \lambda^2 + \omega^2 = 0 \Rightarrow \lambda = \pm i\omega$$

$\text{Re}(\lambda) = 0$ center

clockwise or counterclockwise?

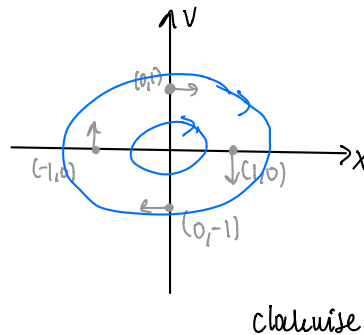
plug in points

At $(1,0)$ $x' = 0$ i.e. down
 $y' = -\omega^2$

At $(0,1)$ $x' = 1$ i.e. right
 $v' = 0$

At $(-1,0)$ $x' = 0$ i.e. up
 $v' = \omega^2$

At $(0,-1)$ $x' = -1$ i.e. left
 $v' = 0$



closed orbit represents the oscillation of the spring - spring moves up and down, velocity of spring also oscillates from + to -.

